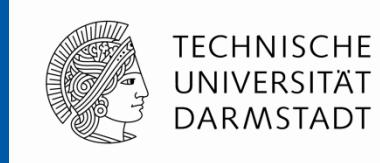


Message Passing with MPI

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HiPerCH



Agenda



TECHNISCHE
UNIVERSITÄT
DARMSTADT

Recap

MPI – Part 1

- Concepts
- Point-to-Point
- Basic Datatypes

MPI – Part 2

The Daily Parallel Life



▶ Multiple Programs Single Data

e.g. Stream Processing or Pipes on the Shell

▶ Single Program Multiple Data (SPMD)

One Program (binary) working on Multiple (parts) of Data

MPI-programs are a typical form of SPMD

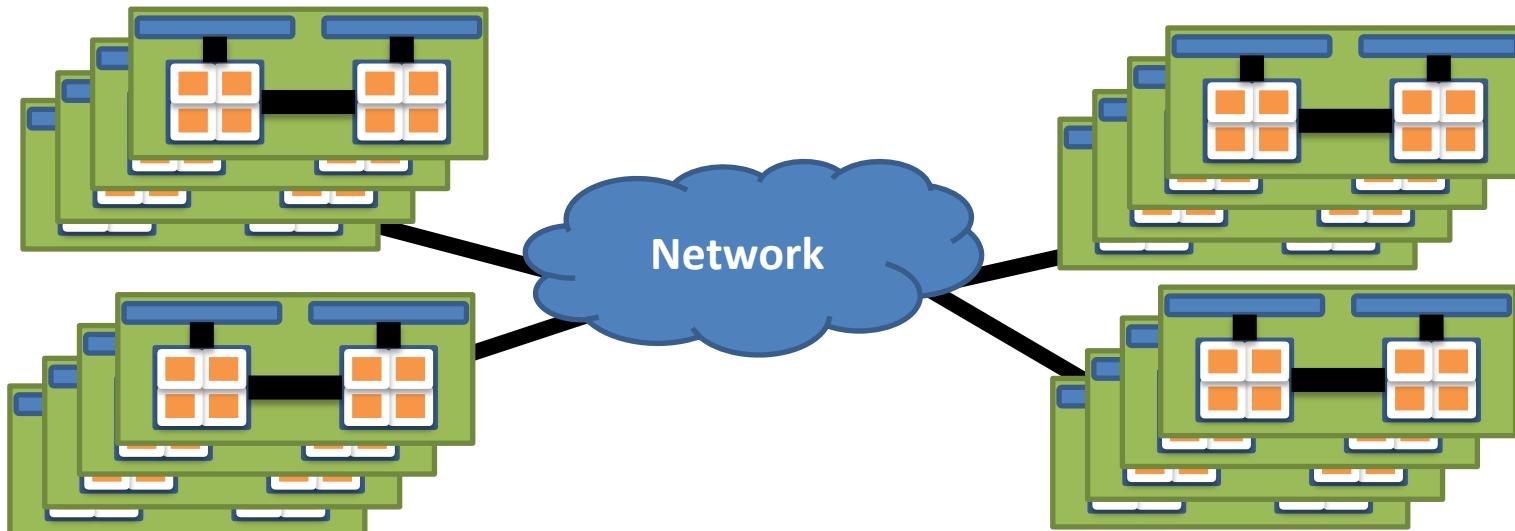
Typically an identification mechanism is used to control the program flow

```
if (myIdentification == special)
{
    do s.th. different
}
else
{
    ...
}
```

- ▶ **Def.: A process is an instance of a computer program**
 - ▶ Executable code: e.g. assembly code
 - ▶ Memory: Heap, Stack, Process-state (CPU-registers, etc.)
 - ▶ One or more threads of execution
 - ▶ Operating-system context
- ▶ **Important:**
 - ▶ Isolation: Once process can not modify any other process without interaction of the operation system
 - ▶ No direct data exchange
 - ▶ No direct synchronization

Clusters

- HPC market is at large dominated by distributed memory multiccomputers and clusters
- Nodes have no direct access to other nodes' memory and usually run their own (possibly stripped down) copy of the OS





- ▶ **Interaction with other processes**

- ▶ Shared Memory
 - ▶ Restriction: Same machine / motherboard
- ▶ File system
 - ▶ Slow, shared file-system required
- ▶ Sockets/networking and named pipes
 - ▶ Coordination/ With whom to communicate
- ▶ Other
 - ▶ Special libraries
 - ▶ **MPI**

Example sockets and network

- ▶ Many different pieces of information necessary
 - ▶ How many communication partners
 - ▶ Where and how can those partners be reached
 - ▶ **Worst case: Full Qualifying Name and Port:**
e.g. linuxnc001.rz.rwth-aachen.de:21587
 - ▶ How to coordinate
 - ▶ Does the user have to start each instance of his parallel program



- ▶ **Identification of participating processes**

- ▶ Who is also working on this problem?

- ▶ **Method to exchange data**

- ▶ Whom to send data?
 - ▶ What kind of data?
 - ▶ How much data?
 - ▶ Has the data arrived?

- ▶ **Method to synchronize**

- ▶ Are we at the same point in the program?

- ▶ **Method to start a set of processes**

- ▶ How do we start processes and get them working together?

→ MPI



Motivation

MPI – Part 1



- Concepts
- Point-to-Point
- Basic Datatypes

MPI – Part 2

The Daily Parallel Life

- ▶ **MPI = Message Passing Interface**
 - a) de-facto standard API for message passing
 - b) Library implementing functionality of the MPI standard
- ▶ **MPI is used to describe (communication) interaction for applications with distributed memory**



▶ MPI Basics

- ▶ Startup, Initialisation, Finalization, Shutdown
- ▶ MPI_Send, MPI_Recv
- ▶ Message-Envelope

▶ Point-to-point Communication

- ▶ Basic MPI-Datatypes
- ▶ MPI_SendRecv
- ▶ MPI_Isend, MPI_Recv, MPI_Wait, MPI_WaitAll, MPI_Query
- ▶ MPI_Bsend, MPI_Brecv
- ▶ MPI_Ssend, MPI_Srecv
- ▶ Common mistakes

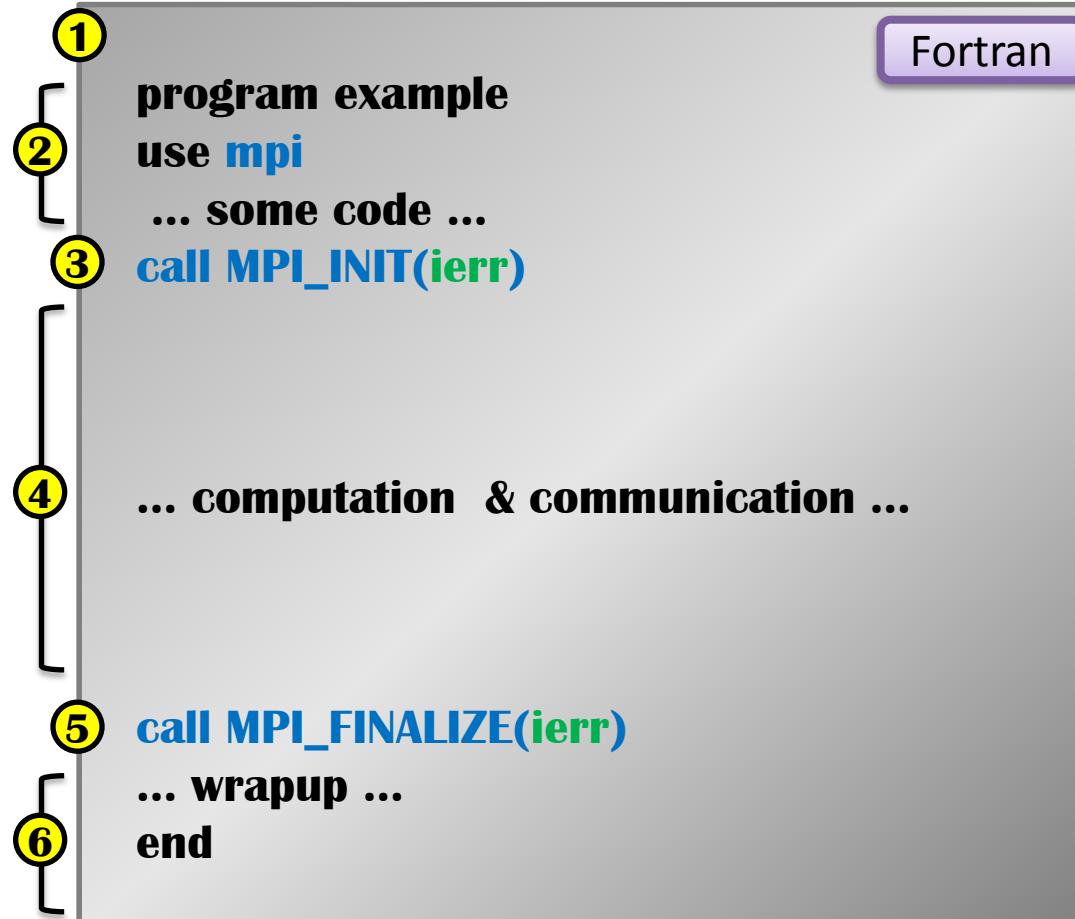
► Startup, Initialization, Finalization, Shutdown for C/C++

```
① #include "mpi.h"
int main(int argc, char ** argv)
{
    ... some code ...
    ③ MPI_Init(&argc,&argv);
    ...
    ④ ... computation & communication ...
    ...
    ⑤ MPI_Finalize();
    ... wrapup ...
    return 0;
}
```

C/C++

- ① Inclusion of the MPI-header
- ② Non coordinated running code: serial
 - NO MPI-calls allowed, few exceptions
 - All program instances run the same code
- ③ Initialization of the MPI Environment
Implicit Synchronization
- ④ User code
Typically computation and communication
- ⑤ Terminate MPI environment
Internal buffers are flushed
- ⑥ Non coordinated running code: serial
 - NO CALLS to MPI functions allowed afterwards

► Startup, Initialization, Finalization, Shutdown for Fortran 90



- 1 Inclusion of the MPI-header
- 2 Non coordinated running code: serial
 - NO MPI-calls allowed, few exceptions
 - All program instances run the same code
- 3 Initialization of the MPI Environment
Implicit Synchronization
- 4 User code
Typically computation and communication
- 5 Terminate MPI environment
Internal buffers are flushed
- 6 Non coordinated running code: serial
 - NO CALLS to MPI functions allowed afterwards

- ▶ How many processes are there?
- ▶ Who am I?

Fortran

program example

include ‘mpif.h’

... some code ...

call MPI_INIT(ierr)

... other code ...

**1 call MPI_COMM_SIZE(MPI_COMM_WORLD,
 numberOfProcs,ierr)**

**2 call MPI_COMM_RANK(MPI_COMM_WORLD,
 myRank,ierr)**

... computation & communication ...

call MPI_FINALIZE(ierr)

... wrapup ...

end

- ① Obtain the number of participating processes of this MPI program instance

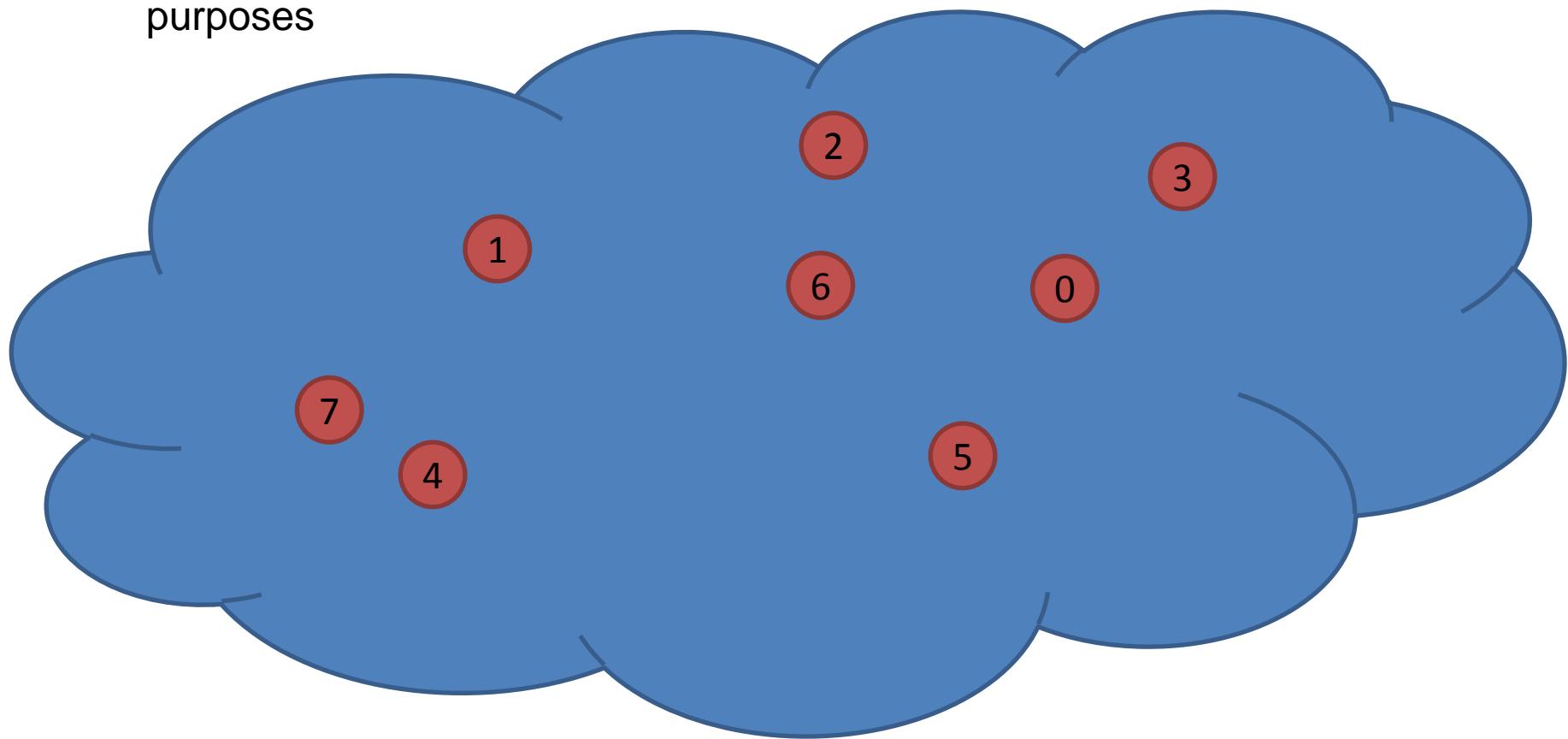
e.g. if there are 2 processes working
numberOfProcs would contain 2 after
the call

- ② Obtain the number of participating processes of this MPI program instance

Note: MPI numbers its processes starting from “0”

E.g. if there are 2 processes working
myRank would either be “0” for the first and “1” for the second process after the call

- ▶ Instances of an MPI-program are initially indistinguishable
- ▶ Only difference obtainable through MPI-calls, typically ranks
 - ▶ getpid() should **not** be used as means of differentiation for communication purposes

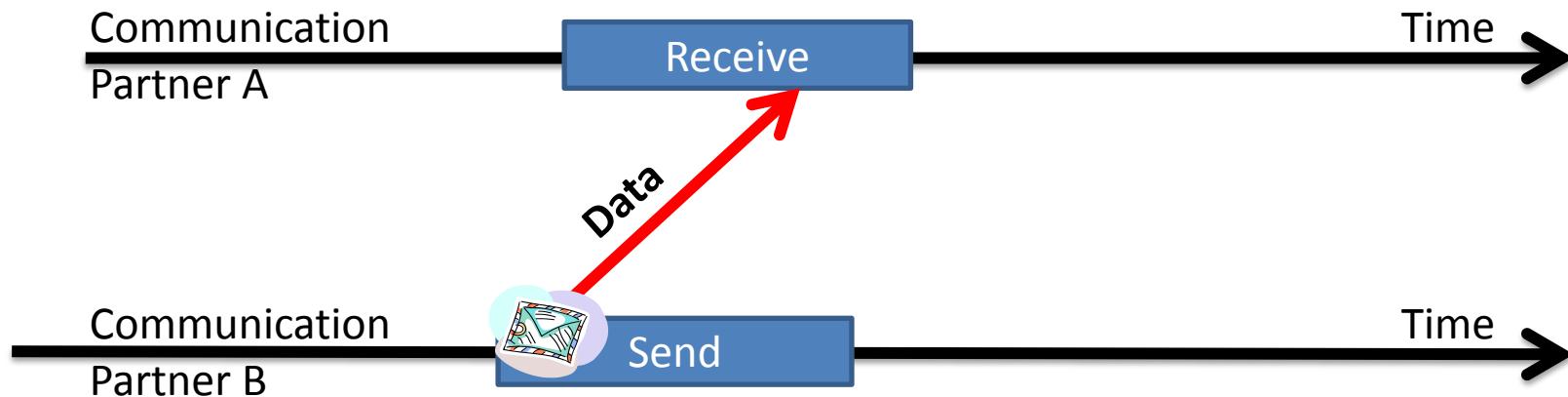




Identification of participating processes

- ▶ Who is also working on this problem?
- ▶ **Method to exchange data**
 - ▶ Whom to send data?
 - ▶ What kind of data?
 - ▶ How much data?
 - ▶ Has the data arrived?
- ▶ **Method to synchronize**
 - ▶ Are we at the same point in the program?
- ▶ **Method to start a set of processes**
 - ▶ How do we start processes and get them working together?

- ▶ Recall: Goal to enable communication of parallel processes with isolated address spaces



- ▶ Required:
Send
Receive
Identification of receiver and sender
Specification of what needs to be send/received



▶ MPI_Send:

```
MPI_Send(void *data, int count, MPI_Datatype type,  
        int dest, int tag, MPI_Comm comm)
```

C/C++

- **data:** memory location containing data
- **count:** number of elements of type “type” to send
- **type:** MPI type of each element
- **dest:** destination rank for the data
- **tag:** identification of message
- **comm:** communicator

```
MPI_SEND(DATA, COUNT, TYPE, DEST, TAG, COMM, IERROR)
```

Fortran



▶ MPI_Recv:

```
MPI_Recv(void *data, int count, MPI_Datatype type,  
        int source, int tag, MPI_Comm comm, MPI_Status * status)
```

C/C++

- **data:** memory location intended for data
- **count:** number of elements of type “type” to send
- **type:** MPI type of each element
- **source:** rank to receive data from
 - Special rank: **MPI_ANY_SOURCE**
- **tag:** identification of message to receive
 - Special tag: **MPI_ANY_TAG**
- **comm:** communicator
- **status:** status of the return
 - Special status: **MPI_STATUS_IGNORE**

```
MPI_RECV(DATA, COUNT, TYPE, DEST, TAG, COMM, STATUS, IERROR)
```

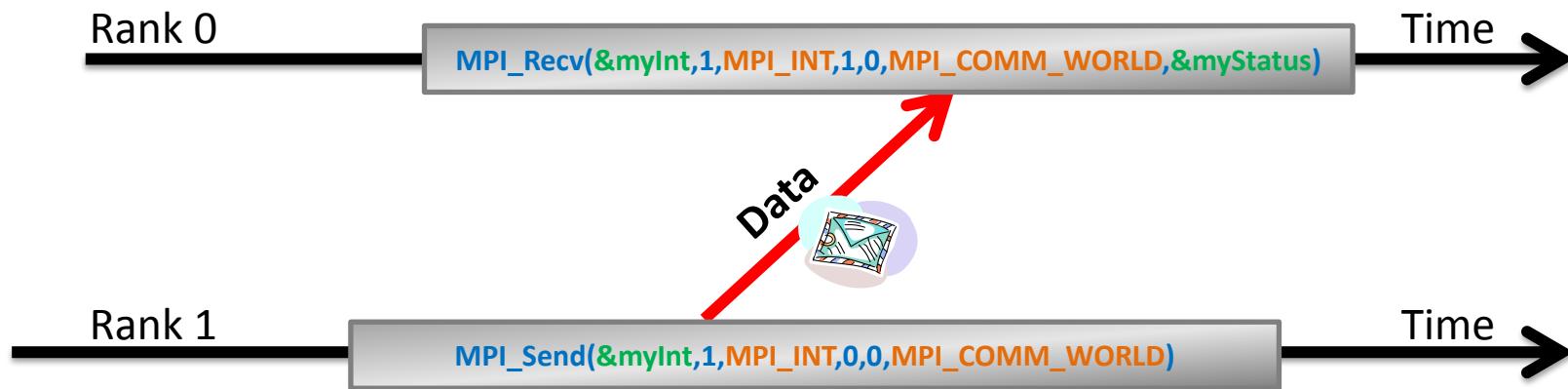
Fortran

- ▶ **(Most) C/C++ - MPI calls have an return value**
e.g.: int MPI_Init(...)
- ▶ **(Most) Fortran - MPI calls have an appended variable for the error-code**
e.g.: MPI_INIT(ierror)
- ▶ **This return value indicates the success**
C/C++: **MPI_SUCCESS == MPI_Init(..)**
Fortran: **call MPI_INIT(ierror)**
 ierror .eq. MPI_SUCCE
or failure otherwise.
- ▶ **Note: returned error-codes are MPI-Implementation specific**

For this presentation no more Fortran calls

MPI – Part 1: Message Passing with MPI

▶ Using MPI-Functions:



- ▶ These two transfer the content of the (integer) variable `myInt` from rank 1 to rank 0



▶ Identification of participating processes

 Who is also working on this problem?

▶ Method to exchange data

 Whom to send data?

 What kind of data?

 How much data?

 Has the data arrived?

▶ Method to synchronize

▶ Are we at the same point in the program?

▶ Method to start a set of processes

▶ How do we start processes and get them working together?

MPI – Part 1: Simple Message Passing Example

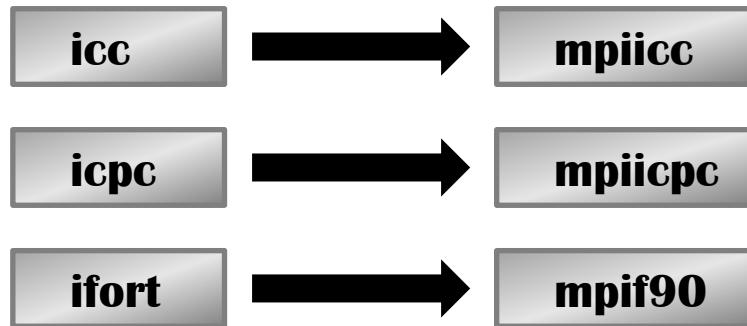
```
#include "mpi.h"
int main(int argc, char ** argv)
{
    int numberOfProcs,myRank,data;
    MPI_Init(&argc,&argv);
    MPI_Comm_size(MPI_COMM_WORLD,
                  &numberOfProcs);
    MPI_Comm_rank(MPI_COMM_WORLD,
                  &myRank);
    if (myRank==0)
        MPI_Recv(&data,1,MPI_INT,1,0,
                 MPI_COMM_WORLD,&status);
    else if (myRank==1)
        MPI_Send(&data,1,MPI_INT,0,0,
                 MPI_COMM_WORLD);
    MPI_Finalize();
    return 0;
}
```

C/C++

- ① Initialization of MPI library
- ② Get identification of processes
- ③ Do s.th. different for each/a process
- ④ Communicate
- ⑤ Stop the MPI library



- ▶ MPI is a typical library
- ▶ For convenience vendors provide specialized compiler wrappers (simply replace regular compiler calls)



```
mpiexec -n <maxprocs> ... <program> <arg1> <arg2> <arg3> ...
```

- ▶ A call to mpiexec starts the maxprocs instances of the program with arguments arg1, arg2, ... and provides the MPI library with enough information to establish its network connections
- ▶ The MPI-standard specifies, but does not require this program



▶ Identification of participating processes

 Who is also working on this problem?

▶ Method to exchange data

 Whom to send data?

 What kind of data?

 How much data?

 Has the data arrived?

▶ Method to synchronize

▶ Are we at the same point in the program?

▶ Method to start a set of processes

 How do we start processes and get them working together?

MPI – Part 1: Message Envelope and Matching



- ▶ Reception of an MPI Message is only controlled by the Message Envelope
- ▶ Recap: MPI_Send

```
MPI_Send(void *data, int count, MPI_Datatype type,  
        int dest, int tag, MPI_Comm comm)
```

C/C++

- ▶ Message Envelope:

	Sender	Receiver
Source	Implicit	Explicit, wildcard possible (MPI_ANY_SOURCE)
Destination	Explicit	Implicit
Tag	Explicit	Explicit, wildcard possible (MPI_ANY_TAG)
Communicator	Explicit	Explicit

- ▶ Recap: MPI_Recv

```
MPI_Recv(void *data, int count, MPI_Datatype type,  
        int source, int tag, MPI_Comm comm, MPI_Status * status)
```

C/C++

MPI – Part 1: Message Envelope and Matching

- ▶ **Caveat: Reception of an MPI Message is also dependent on the data**
- ▶ **Recap:**

```
MPI_Send(void *data, int count, MPI_Datatype type,  
        int dest, int tag, MPI_Comm comm)
```

C/C++

```
MPI_Recv(void *data, int count, MPI_Datatype type,  
        int source, int tag, MPI_Comm comm, MPI_Status * status)
```

C/C++

- ▶ **The standard expects data types to match**
 - ▶ NOT ENFORCED BY THE IMPLEMENTATIONS
- ▶ **For a receive to complete also enough data has to have arrived**

Rank 0:

```
MPI_Send(myVar,1,MPI_INT,1,0,MPI_COMM_WORLD)  
... some code ...  
MPI_Send(myVar,1,MPI_INT,1,0,MPI_COMM_WORLD)
```

Rank 1:

```
MPI_Recv(myVar,2,MPI_INT,0,0,MPI_COMM_WORLD,stat)  
... some code ...
```

Incomplete



- **The receive buffer must be able to hold the whole message**
 - send count \leq receive count -> **OK** (but check status)
 - send count $>$ receive count -> **ERROR** (message truncated)

The MPI status object holds information about the received message

C/C++: MPI_Status status

- `status.MPI_SOURCE` message source rank
- `status.MPI_TAG` message tag
- `status.MPI_ERROR` receive status code

Fortran: INTEGER, DIMENSION(MPI_STATUS_SIZE) :: status

- `status(MPI_SOURCE)` message source rank
- `status(MPI_TAG)` message tag
- `status(MPI_ERROR)` receive status code



► MPI provides many predefined data types

► Fortran:

MPI datatype	Fortran datatype
MPI_INTEGER	INTEGER
MPI_REAL	REAL
MPI_DOUBLE_PRECISION	DOUBLE PRECISION
MPI_COMPLEX	COMPLEX
MPI_LOGICAL	LOGICAL
MPI_CHARACTER	CHARACTER(1)
MPI_BYTE	n.a.
...	...

- C/C++
- Userdefined datatypes

8 binary digits



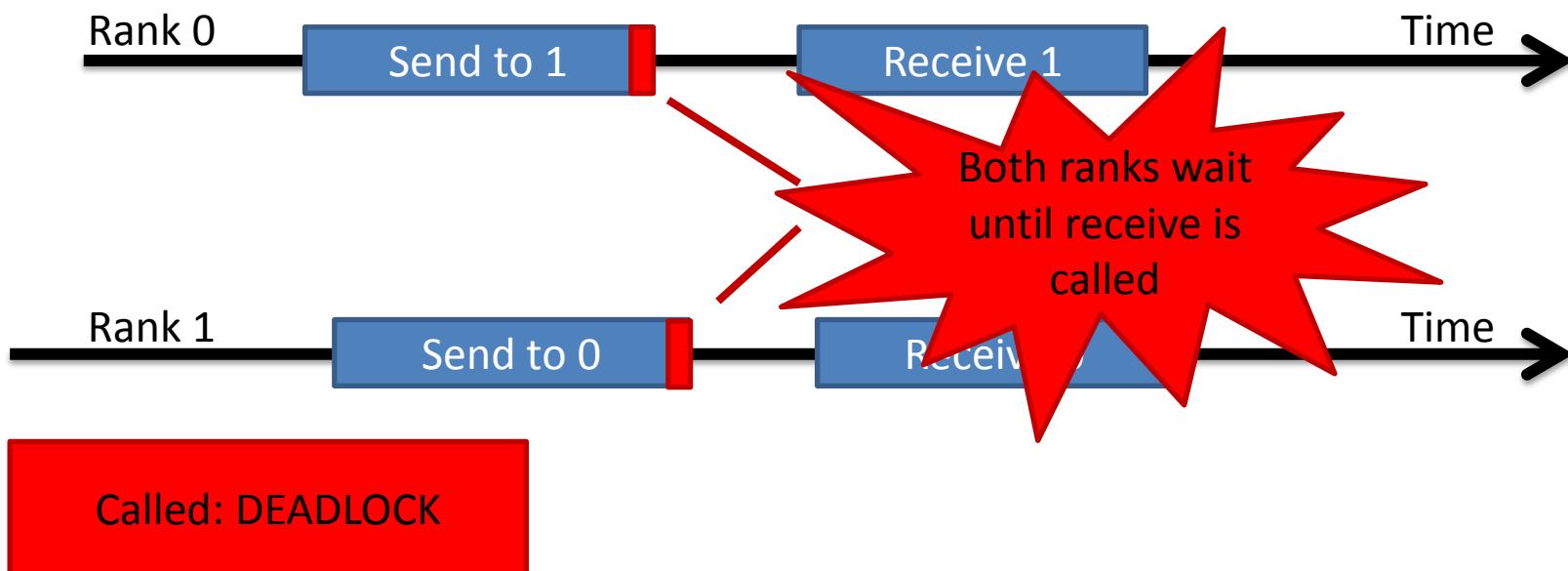
► MPI provides many predefined data types

- Fortran
- C/C++:

MPI datatype	Fortran datatype
MPI_CHAR	char
MPI_SHORT	signed short int
MPI_INT	signed int
MPI_FLOAT	float
MPI_DOUBLE	double
MPI_UNSIGNED_CHAR	unsigned char
...	...
MPI_BYTE	n.a.

- Userdefined datatypes

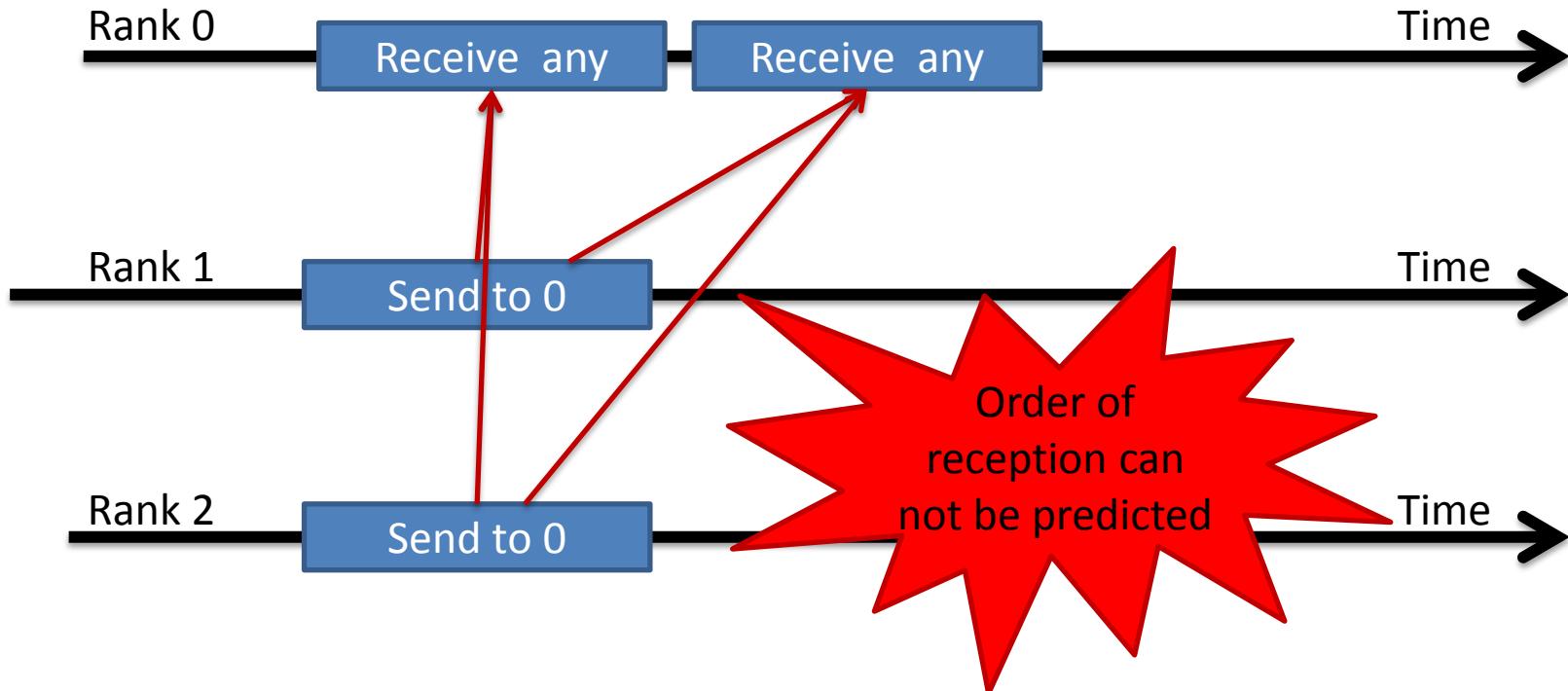
- ▶ All MPI function calls are blocking
 - ▶ Except when explicitly specified differently
 - ▶ Function call only returns once its operation has completed
 - ▶ NOTE: MPI_Send and MPI_Recv are blocking
- ▶ Example:





▶ Example:

In which order are the messages arriving?



Called: RACE CONDITION

MPI – Part 1: MPI_Sendrecv (1/2)

```
MPI_Sendrecv(void *sendData, int sendCount, MPI_Datatype sendType,
int dest, int sendTag, void * recvData, int recvCount,
MPI_Datatype recvType, int source, int recvTag, MPI_Comm comm,
MPI_Status * status)
```

C/C++

- **Arguments:**

	Send	Receive
Data	sendData	recvData
Count	sendCount	recvCount
Type	sendType	recvType
Destination	Dest	- n.a. -
Source	- n.a. -	Src
Tag	sendTag	recvTag

- comm: common communicator
- status: status of the recv-part



▶ Note:

- ▶ MPI_Sendrecv sends only one message and receives one message
- ▶ The send and the receive – data may not overlap
use MPI_Sendrecv_replace instead:

```
MPI_Sendrecv_replace(void *data, int count, MPI_Datatype dataType,  
int dest, int sendTag, int source, int recvTag, MPI_Comm comm,  
MPI_Status * status)
```

C/C++

- ▶ First send data, then receive (same amount of) data to the same memory location



- ▶ The MPI_Status struct contains information about the received message:

“source” of the message:

MPI_SOURCE field of the struct

“tag” of the message:

MPI_TAG field of the struct

„error code“ of the receive operation:

MPI_ERROR field of the struct

“size” of the message:

Next slide!



MPI_Probe(int source, int tag, MPI_Comm comm, MPI_Status * status)

C/C++

- ▶ Query if a message from source with tag is available
- ▶ Message is not received
- ▶ Information about the matched message is stored in the status field
- ▶ E.g.: Is there any message?

**MPI_Probe(MPI_ANY_SOURCE,MPI_ANY_TAG,
MPI_COMM_WORLD, &status)**

C/C++

- ▶ Note: **MPI_Probe** is blocking!

MPI_Get_count(MPI_Status * status, MPI_Datatype datatype, int * count)

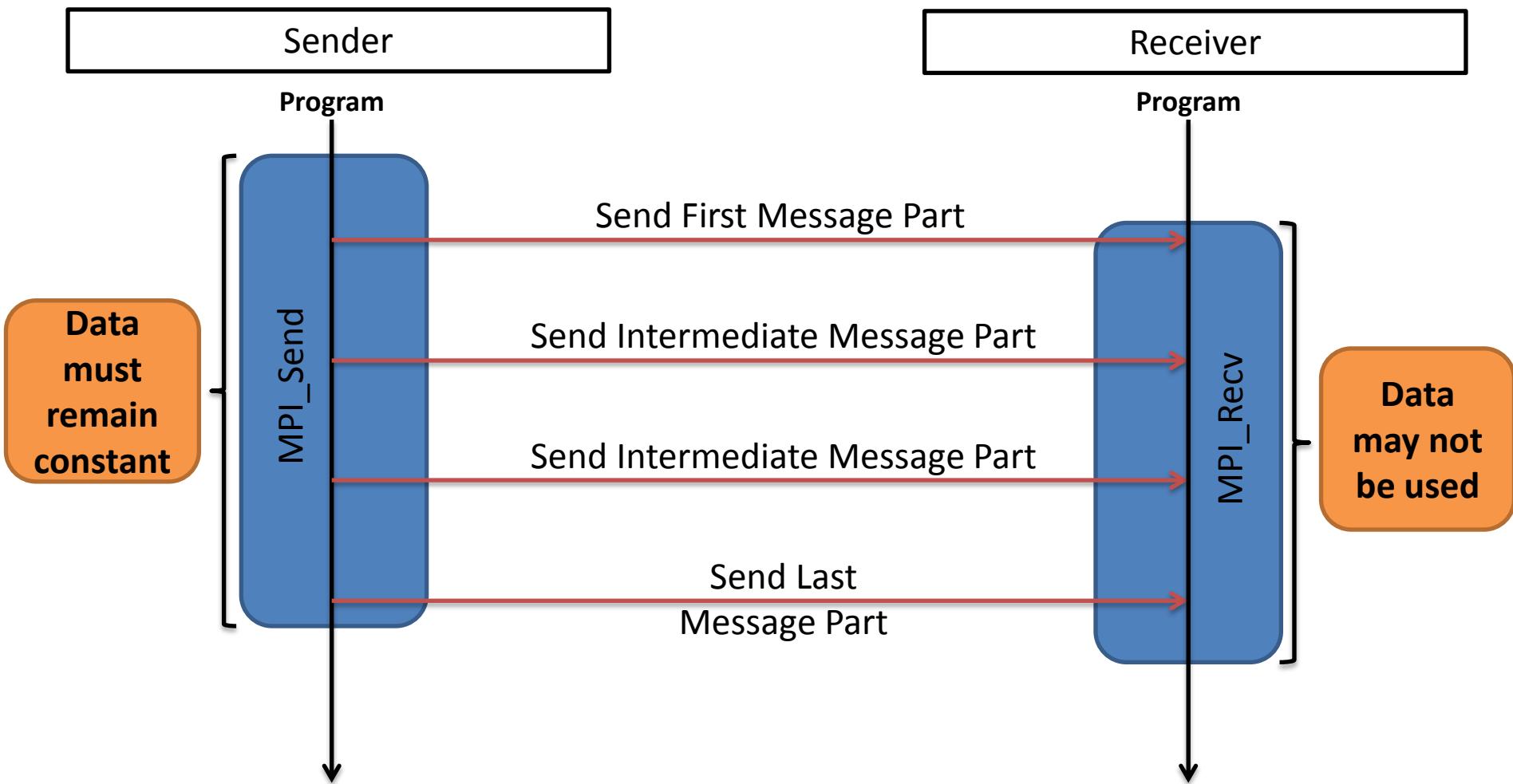
C/C++

- ▶ Compute how many elements of **datatype** could be formed from the (unreceived) message referenced by **status**

MPI – Part 1: Non-Blocking communication (1 / 6)



► (Blocking) MPI_Send / MPI_Recv:



MPI – Part 1: Non-Blocking communication (2 / 6)



- ▶ **MPI_Isend / MPI_Irecv:** start an nonblocking asynchronous communication

```
MPI_Isend(void * data, int count, MPI_Datatype dataType,  
          int dest, int tag, MPI_Comm comm, MPI_Request * request)
```

C/C++

```
MPI_Irecv(void * data, int count, MPI_Datatype dataType,  
          int source, int tag, MPI_Comm comm, MPI_Request * request)
```

C/C++

- **request:** Handle to reference the started communication
- ▶ **MPI_Wait:** wait for the referenced communication operation to finish

```
MPI_Wait (MPI_Request * request, MPI_Status * status)
```

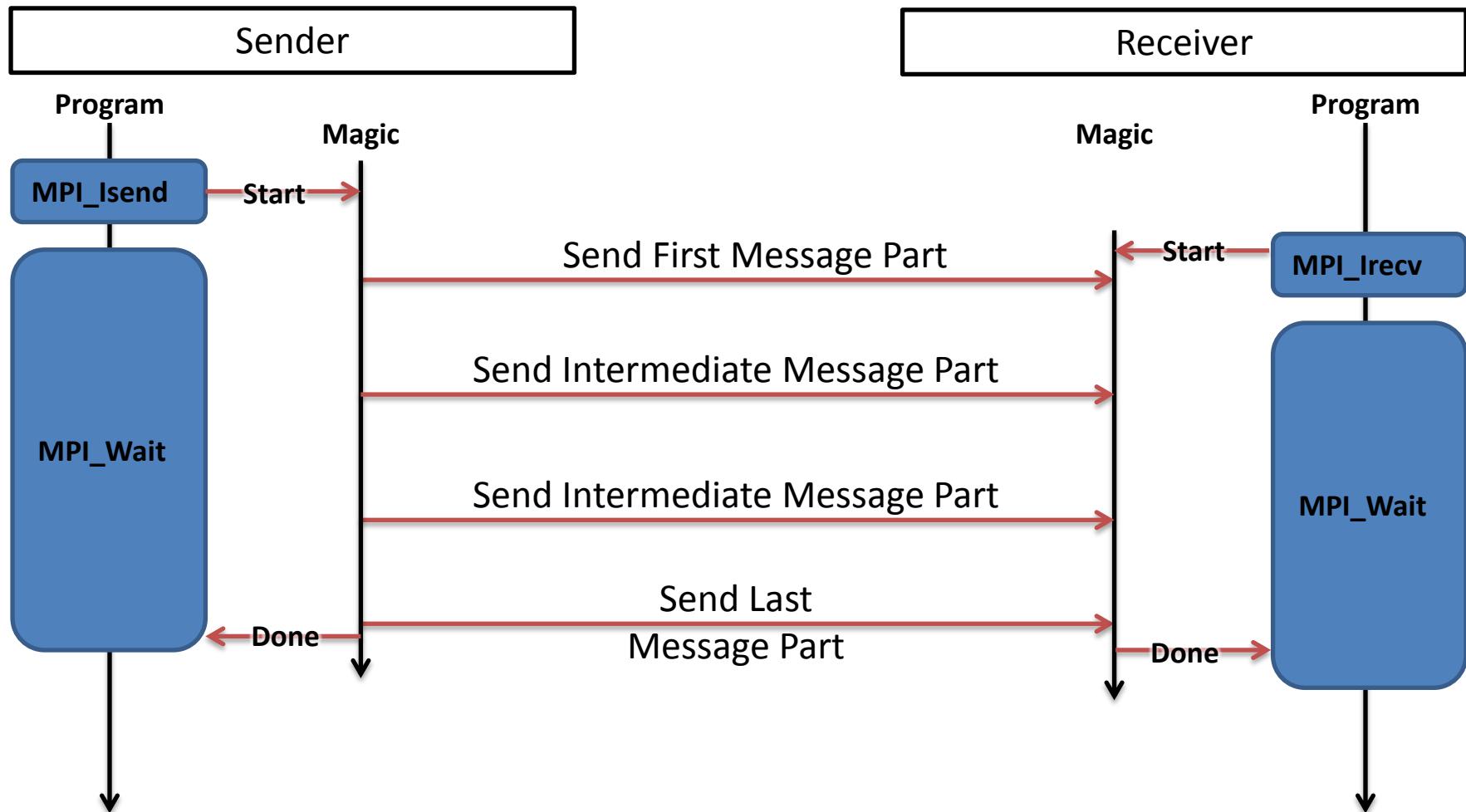
C/C++

- **request:** Handle to a previously started communication
- **status:** filled by MPI_Wait with the status of the completed communication

MPI – Part 1: Non-Blocking communication (3 / 6)



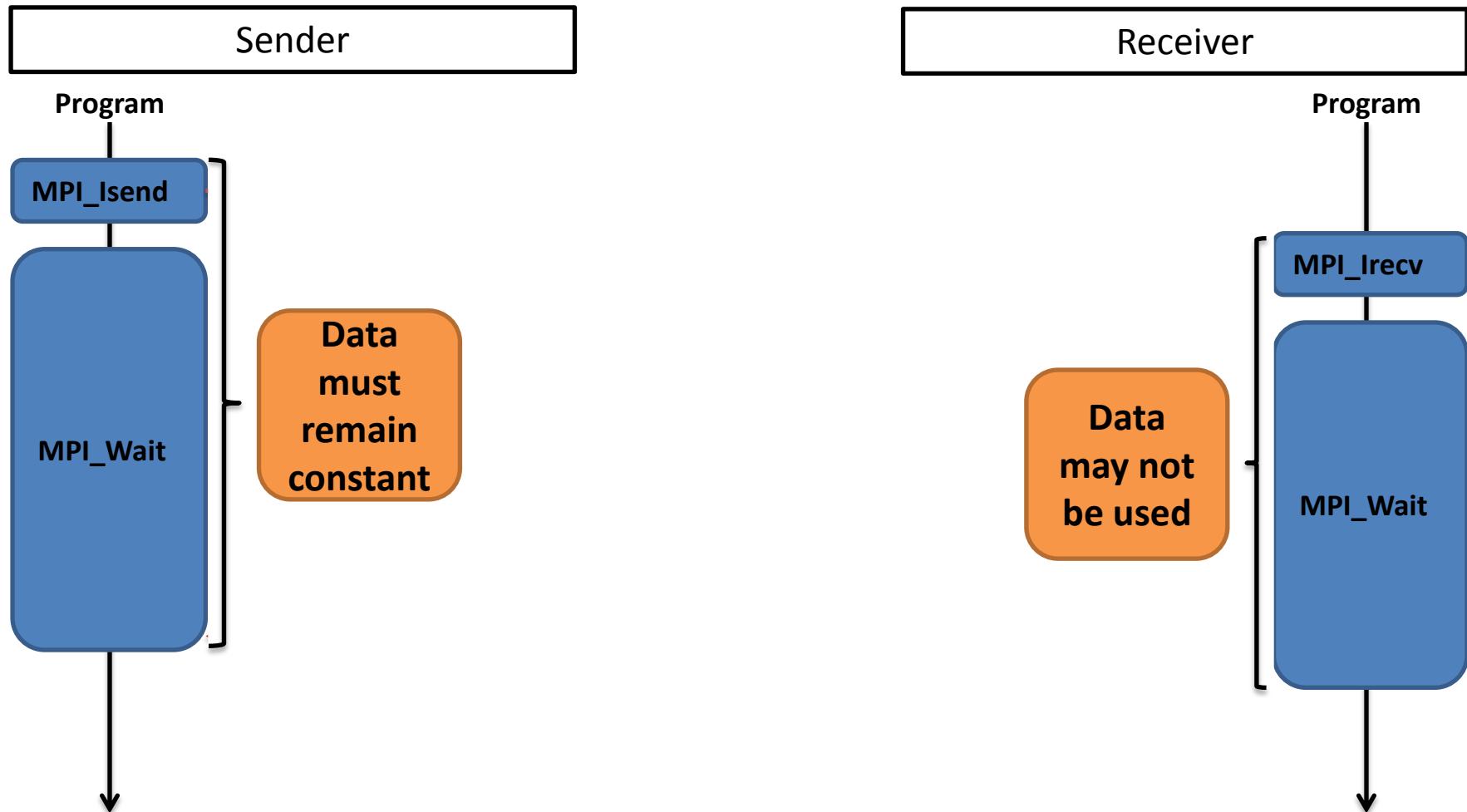
▶ MPI_Isend / MPI_Irecv/MPI_Wait:



MPI – Part 1: Non-Blocking communication (3 / 6)



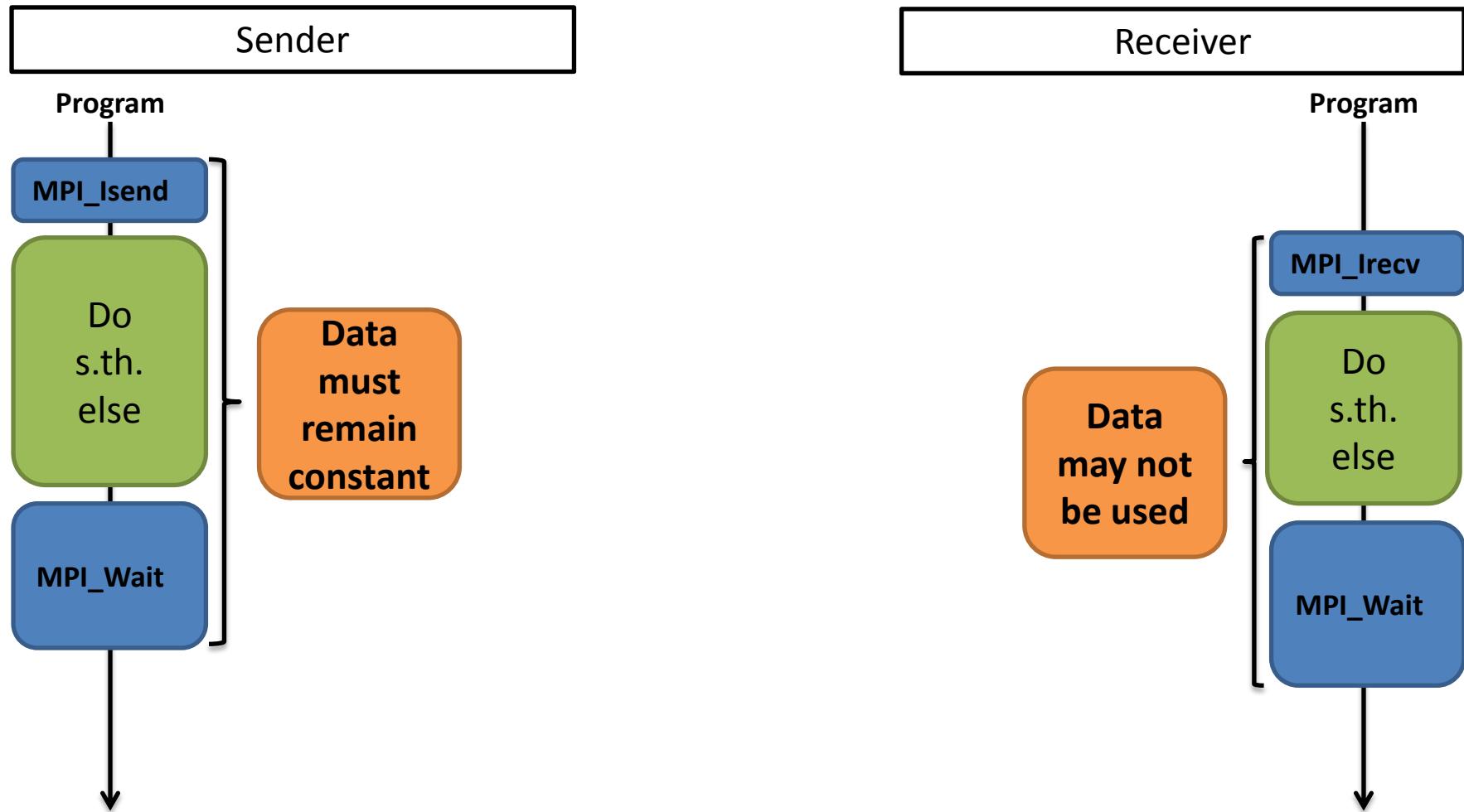
▶ MPI_Isend / MPI_Irecv/MPI_Wait:



MPI – Part 1: Non-Blocking communication (4 / 6)



▶ MPI_Isend / MPI_Irecv/MPI_Wait:





- ▶ Testing and waiting
- ▶ MPI_TEST: test if given request has finished without blocking

`MPI_Test(MPI_Request * request, int * flag, MPI_Status * status)`

C/C++

- flag: is set to true if request has finished otherwise not
- status: contains status of operation if test was successful
- ▶ Note: the request is considered completed and set to MPI_REQUEST_NULL
- ▶ MPI_REQUEST_GET_STATUS: similar to MPI_TEST, but does not complete the request

`MPI_Request_get_status(MPI_Request * request, int * flag,
MPI_Status * status)`

C/C++



▶ Other test and wait functions

- ▶ **MPI_Request_free**
Free a request handle, communication will complete
- ▶ **MPI_Wait_any**
Wait for multiple requests, block until one completes
- ▶ **MPI_Test_any**
Test for multiple requests without blocking, only one request is free
- ▶ **MPI_Wait_all**
Wait for all requests
- ▶ **MPI_Wait_some**
Wait for one or more requests, all completed requests are freed
- ▶ **MPI_Test_some**
Test for one or more request, all completed requests are freed



- ▶ **MPI supports 4 send modes:**
 - ▶ Standard
 - ▶ Buffered
 - ▶ Synchronous
 - ▶ Ready
- ▶ **Note: Only 1 receive mode**



▶ **Normal Blocking Send Mode:**

The call blocks until the message-data and envelope have been copied to internal buffers or been used to send a message

▶ **Buffered Send Mode:**

Letter Prefix: B

The call blocks until the envelope and all of the message-data has been copied to an MPI-internal buffer.

Transmission occurs at a potential later point

▶ **Synchronous Send Mode:**

Letter Prefix: S

The call blocks until a matching receive has been called and the envelope and data has been put aside or transmitted

▶ **Ready Send Mode:**

Letter Prefix: R

May only be called if the matching receive has been posted.

Behavior as normal send



▶ Function names:

- ▶ MPI_Bsend
- ▶ MPI_Ibsend
- ▶ MPI_Ssend
- ▶ MPI_Issend
- ▶ MPI_Rsend
- ▶ MPI_Irsend

▶ Specify buffer for buffered send

- ▶ MPI_Buffer_attach
- ▶ MPI_Buffer_detach



► MPI_Abort: Try to abort all collaborating MPI-processes

`MPI_Abort(MPI_Comm comm, int errorcode)`

C/C++

- Attempt to abort the MPI program returning errorcode if possible

MPI_Wtime:

`double MPI_Wtime()`

C/C++

- **MPI_Wtime** returns the (fraction-) number of seconds since some arbitrary point of time

► MPI_Get_processor_name: Get a name for the current node hosting the MPI-process

`MPI_Get_processor_name(char * data,int * maxLen)`

C/C++

- **data:** data contains a string identifying the executing host
- **maxLen:** variable initialized with the maximum string length



▶ Further utility functions:

`MPI_Wtick`

`MPI_Inizialized`

`MPI_Finalized`



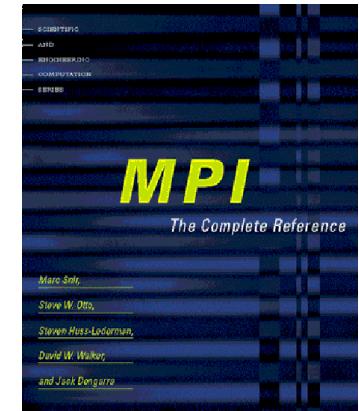
- ▶ **Version 1.0 (1994): Fortran77 and C supported**
- ▶ **Version 1.1 (1995): Minor corrections and clarifications**
- ▶ **Version 1.2 (1997): Further corrections and clarifications**
- ▶ **Version 2.0 (1997): Major enhancements:**
 - ▶ One-sided communications
 - ▶ Parallel IO (p.d. add-on: ROMIO)
 - ▶ Dynamic process generation
 - ▶ Fortran 90 and C++ support
 - ▶ Thread Safety
 - ▶ Language interoperability
- ▶ **Version 2.1 (2008): Merging of MPI-1 and MPI-2**
- ▶ **Version 2.2 (2009): Minor correction and clarifications**

- ▶ **Version 3.0 (in the works):**
 - ▶ Non blocking collectives
 - ▶ Scalability issues

▶ MPI. The Complete Reference Vol. 1: The MPI core. Second edition

by Marc Snir, Steve Otto, Steven Huss-Lederman,
David Walker, Jack Dongarra.

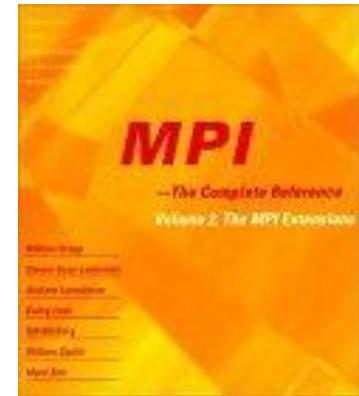
The MIT Press; 2 edition; 1998



▶ MPI: The Complete Reference. Vol 2: The MPI-2 extensions

by William Gropp, Steven Huss-Lederman,
Andrew Lumsdaine, Ewing Lusk, Bill Nitzberg,
William Saphir, Marc Snir

The MIT Press; 2nd edition; 1998



▶ Using MPI

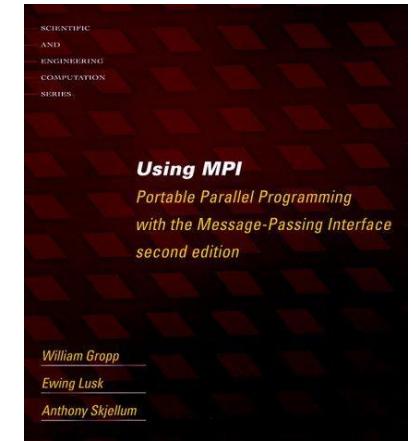
by William Gropp, Ewing Lusk, Anthony Skjellum

The MIT Press, Cambridge, London 1999

▶ Using MPI-2

William Gropp, Ewing Lusk, Rajeev Thakur

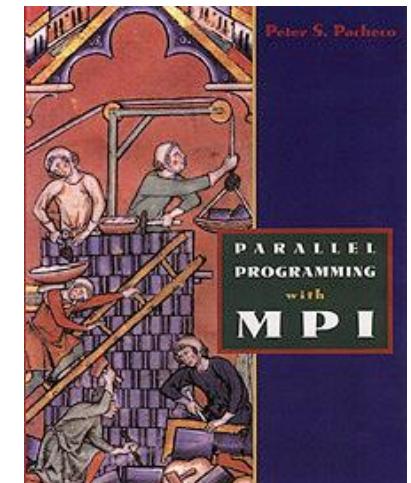
The MIT Press, Cambridge, London 2000



▶ Parallel Programming With MPI

by Peter Pacheco

440 Seiten - Morgan Kaufmann Publishers





- ▶ **The MPI Forum**
 - ▶ <http://www mpi-forum.org/>
- ▶ **The MPI home page at Argonne National Lab**
 - ▶ <http://www-unix.mcs.anl.gov/mpi/>
 - ▶ <http://www.mcs.anl.gov/research/projects/mpi/www/>
- ▶ **Open-MPI**
 - ▶ <http://www.open-mpi.org/>
- ▶ **Our MPI web page with further links**
 - ▶ <http://www.rz.rwth-aachen.de/mpi/>
- ▶ **Manual pages**
 - ▶ man MPI
 - ▶ man mprun
 - ▶ man MPI_Xxxx (for all MPI calls)



UP NEXT: **MPI PART 2**